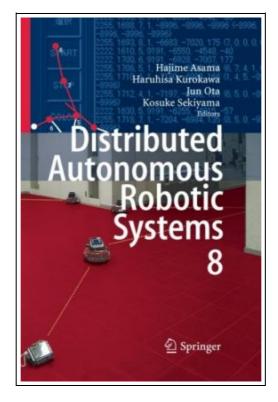
# Distributed Autonomous Robotic Systems 8



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Condition: New. Publisher/Verlag: Springer, Berlin | The 9th DARS symposium was held during November 17-19 in Tsukuba, Japan. This volume not only offers readers the latest research results related to DARS from theoretical studies to application-oriented ones, it also describes the present trends of this field. | The International Symposia on Distributed Autonomous Robotic Systems (DARS) started at Riken, Japan in 1992. Since then, the DARS symposia have been held every two years: in 1994 and 1996 in Japan (Riken, Wako), in 1998 in Germany (Karlsruhe), in 2000 in the USA (Knoxville, TN), in 2002 in Japan (Fukuoka), in 2004 in France (Toulouse), and in 2006 in the USA (Minneapolis, MN). The 9th DARS symposium, which was held during November 17-19 in T- kuba, Japan, hosted 84 participants from 13 countries. The 48 papers presented there were selected through rigorous peer review with a 50% acceptance ratio. Along with three invited talks, they addressed the spreading research fields of DARS, which are classifiable along two streams: theoretical and standard studies of DARS, and interdisciplinary studies using DARS concepts. The former stream includes multi-robot cooperation (task assignment methodology among multiple robots, multi-robot localization, etc.), swarm intelligence, and modular robots. The latter includes distributed sensing, mobiligence, ambient intelligence, and mul- agent systems interaction with human beings. This book not only offers readers the latest research results related to DARS from theoretical studies to application-oriented ones; it also describes the present trends of this field. With the diversity and depth revealed herein, we expect that DARS technologies will flourish soon. | Distributed Sensing.- Multi-Robot Uniform Frequency Coverage of Significant Locations in the Environment.- Measuring the Accuracy of Distributed Algorithms on Multi-robot Systems with Dynamic Network Topologies.- Network Topology Reconfiguration Based on Risk Management.- Energy-Efficient Distributed Target Track

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